

Sloat Boulevard Quick-Build Project

Winter 2023

FOR MORE INFORMATION

visit: SFMTA.com/SloatQB

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Project Focus

The Sloat Quick-Build seeks to improve traffic safety for all modes on a segment of the City's High-Injury Network.

The project intends to better connect recreational and institutional spaces in the area for people on foot and bikes, including Lake Merced, the San Francisco Zoo, and Ocean Beach.

The project will connect with other projects, such as the Great Highway Extension closure and Lake Merced Quick-Build to provide a seamless route for people biking through the City's southwest corner.

Project Map



Project limits: Great Highway and Skyline Boulevard







Vision Zero and the Quick-Build Program

Vision Zero is a citywide policy with the goal of eliminating all serious and fatal traffic collisions. The **Vision Zero Quick-Build Program** is an SFMTA effort to quickly implement pedestrian and bicycle safety improvements on the Vision Zero High Injury Network. The SFMTA implements quick-build safety projects to decrease the number of people fatally and severely injured on San Francisco streets, resulting in progress towards the SFMTA's Vision Zero commitment. Learn more at SFMTA.com/QuickBuild.

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Project Design Elements

The project team will employ a tailored set of quickbuild design elements to improve safety and access for people walking and biking, including:

A two-way protected bikeway on the south side of Sloat physically separate people riding bikes from people driving.



Bus boarding islands provide level, in-roadway boarding for people riding the 18 and 23 bus lines. The project will evaluate consolidation of low-ridership stops to improve transit reliability and minimize parking removal.



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Painted safety zones at unsignalized intersections increase pedestrian visibility and shorten crossings.



Parking and loading changes near the Zoo entrance maximize access to corridor destinations for all users.



Timeline

Winter 2023 Spring 2023 Mid-Late 2023

Public Outreach

Project Approvals

Implementation